

# Frequency Measurement and Sub-Ns Phase fit for the GSI/FAIR Bunch-to-Bucket System

Synchrotron

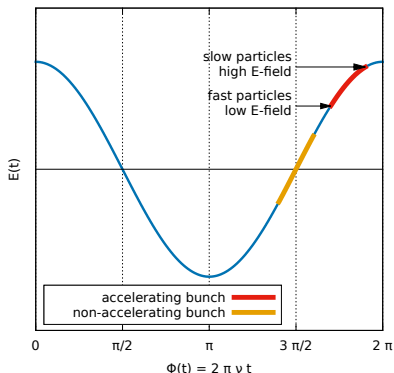
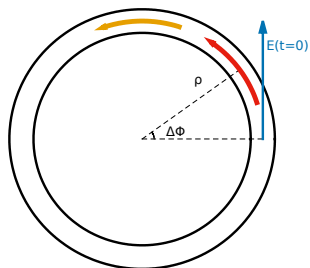
B2B System

Frequency Measurement

Sub-ns Phase Fit

# Synchrotron Accelerator

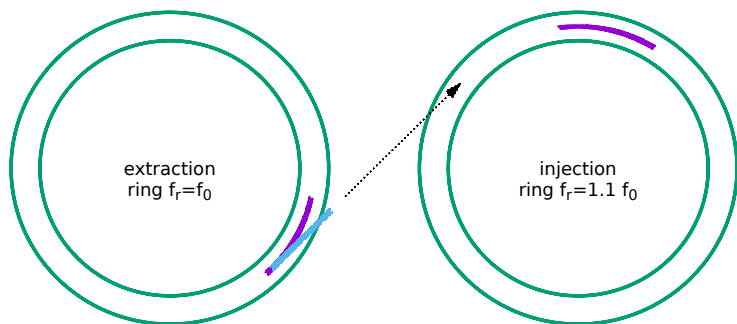
- ▶ Orbit of constant radius  $\rho$  and revolution frequency  $f_r$ . (Rigidity  $B\rho = p/q$ )
- ▶ RF system at a distinct place on the ring with frequency  $\nu = h f_r$



## Bunches and Buckets

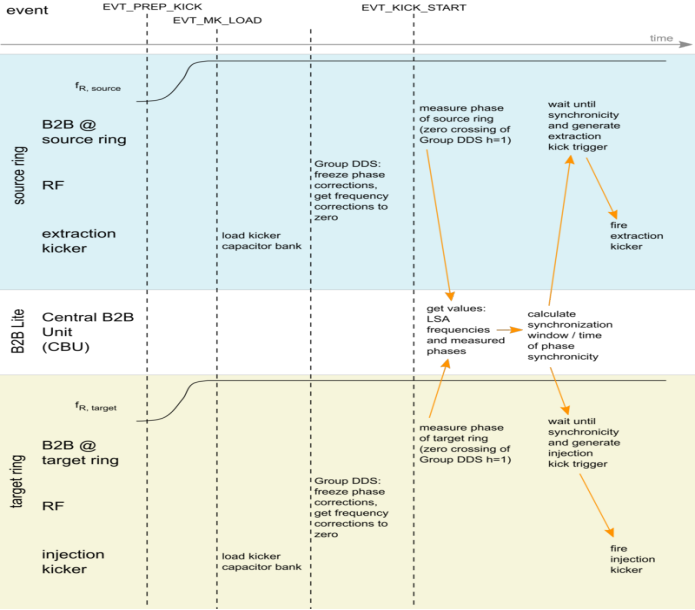
- ▶ Bunch: Set of particles with a stable orbit and longitudinal focusing by the RF
- ▶ Bucket: Time dependent stable bunch location inside the synchrotron

## B2B Frequency Beating Method



- ▶ RF for extraction ring and injecting ring are slightly de-tuned:  $\nu_{\text{extr}} \approx \nu_{\text{inj}}$
- ▶ Possibility of transfer occurs with the beating frequency:  $\nu_{\text{extr}} - \nu_{\text{inj}}$
- ▶ Transfer time can be calculated from relative phases of  $\text{RF}_{\text{extr}}$  and  $\text{RF}_{\text{inj}}$

# B2B Procedure



by D.Beck

# B2B System

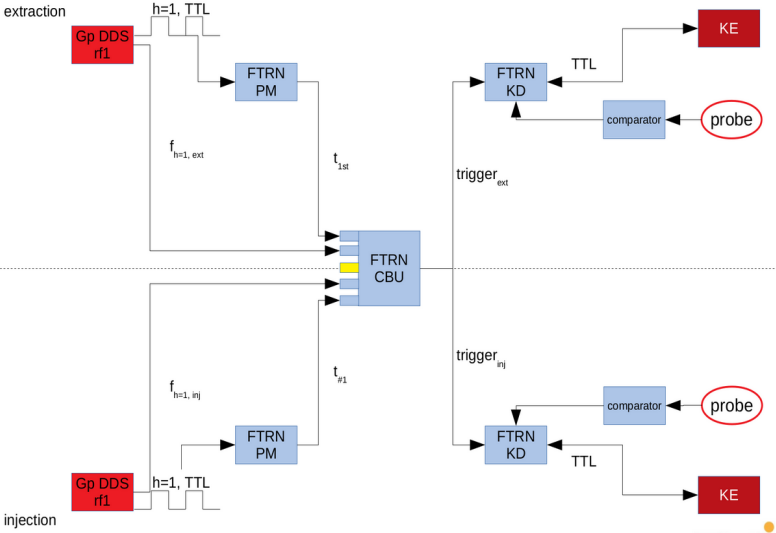


Figure: Extraction (top) and injection (bottom).

by D.Beck

# Frequency Measurement: Motivation

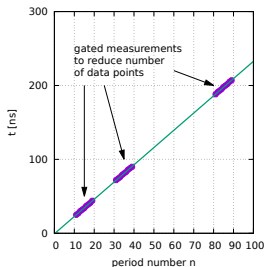
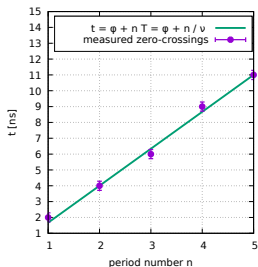
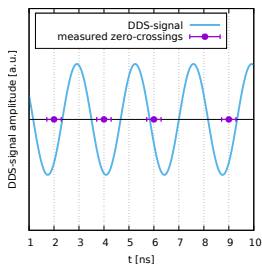
## Independent measurement of DDS output frequency $\nu$

- ▶ verify RF set value
- ▶ implicit check of WhiteRabbit and Butis synchronization
- ▶ hardware is already there
  - ▶ comparator units
  - ▶ 1 ns TLU (TDC) from B2B-PM unit
- ▶ only software development

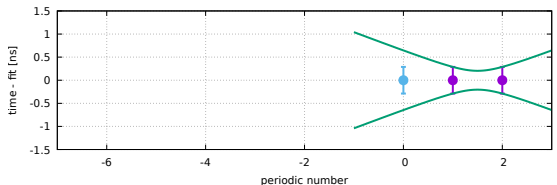
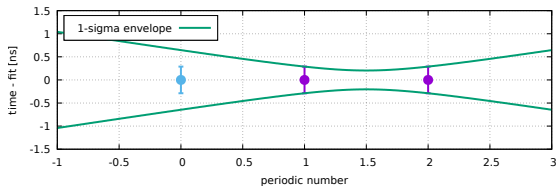
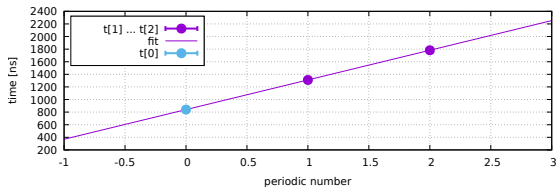
# Implementation

## Basic idea

- ▶ B2B-PM firmware measures 3 data sets during RF-flat-top
- ▶ straight-line fit to the data (period number, zero-crossing time)
- ▶ frequency  $\nu$  and phase  $\varphi$  are fit parameters
- ▶ period number is not measured  $\Rightarrow$  iterative fit
  - ▶ calculate period number using fit to previous data
  - ▶ identify outlier using the variance of the fit to previous data



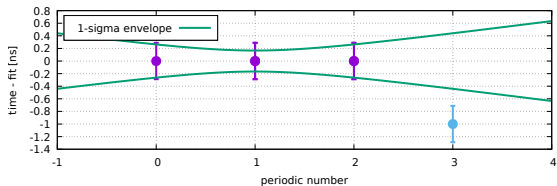
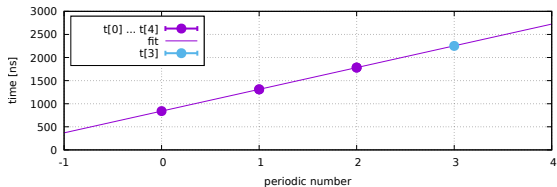
# Iterative Fit



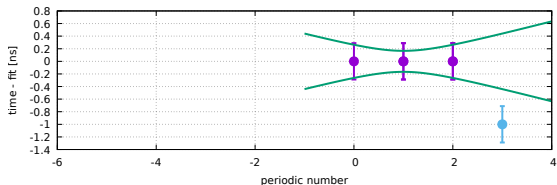
- ▶ fit to points 1,2
- ▶ check if point 0 is close enough  $< 6\sigma$  to the fit
- ▶ yes  $\Rightarrow$  include point 0 in the fit



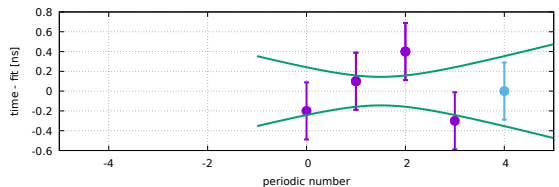
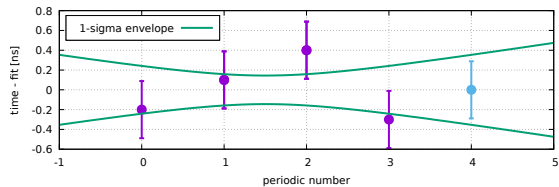
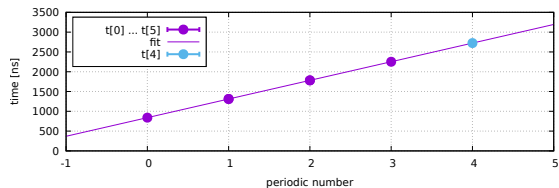
# Iterative Fit



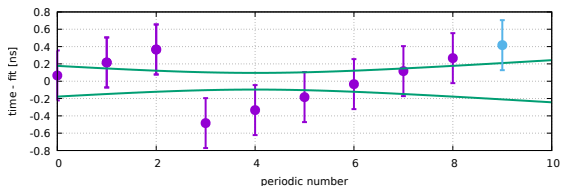
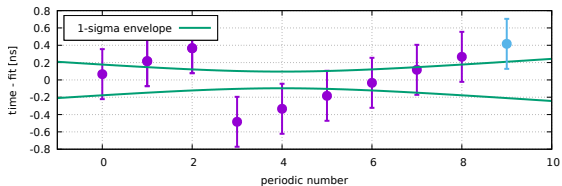
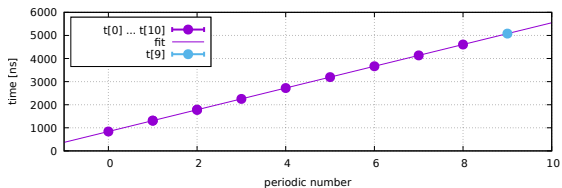
- ▶ check if point n close to the fit
- ▶ yes  $\Rightarrow$  include point n in the fit



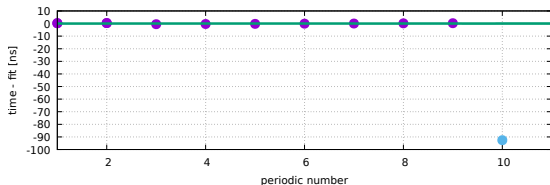
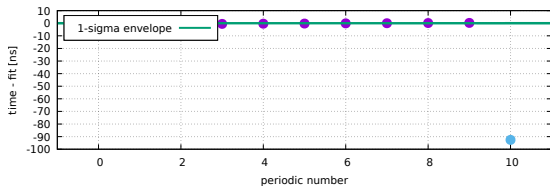
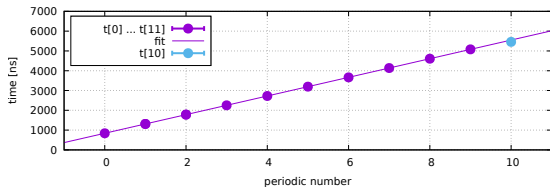
# Iterative Fit



# Iterative Fit

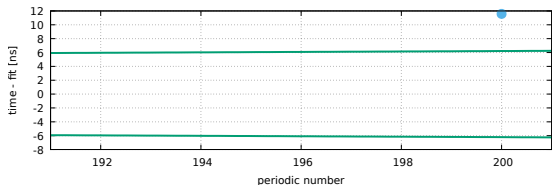
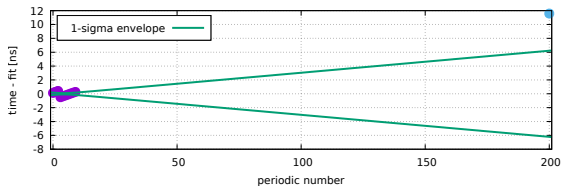
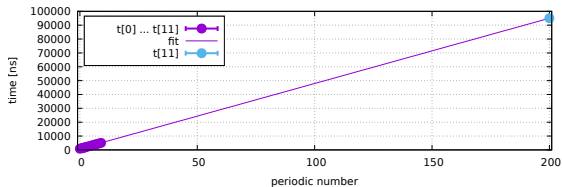


# Iterative Fit



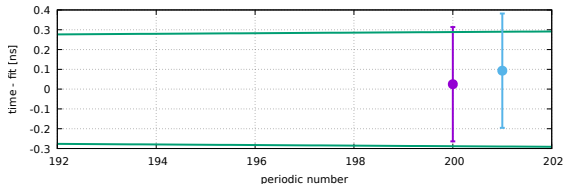
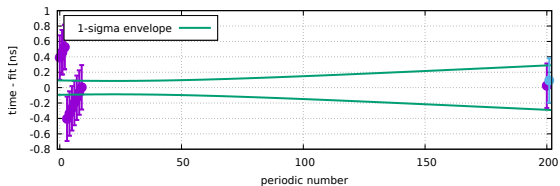
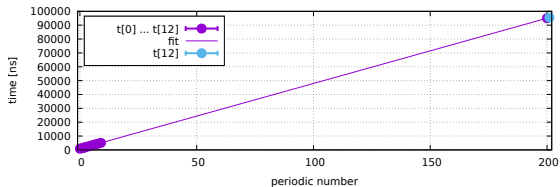
- ▶ detect outlier caused by the closing gate on the input (no real zero-crossing)

# Iterative Fit



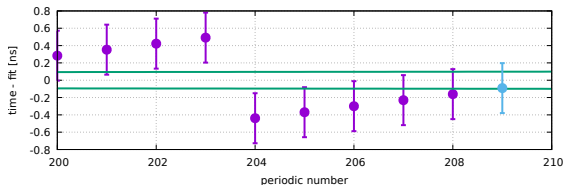
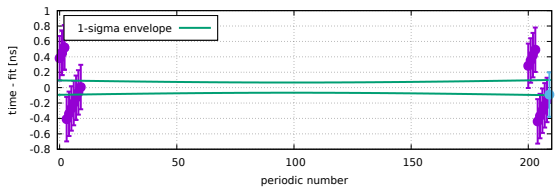
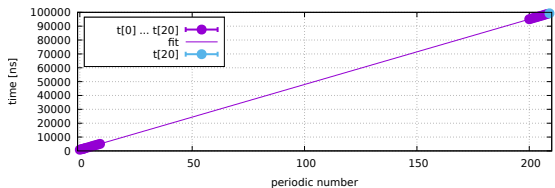
- ▶ fit to the previous data is good enough to bridge the gap to the next gate
- ▶ this allows to calculate the period number reliably

# Iterative Fit

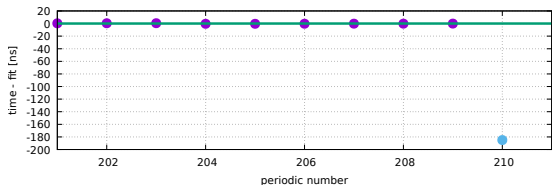
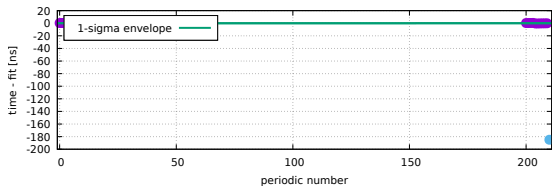
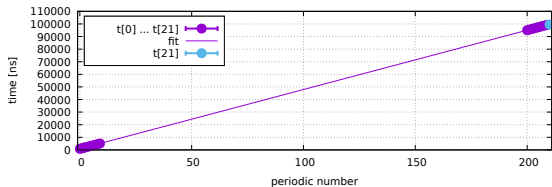


- ▶ including the first point of the next data burst drastically improves the fit because of the long lever

# Iterative Fit



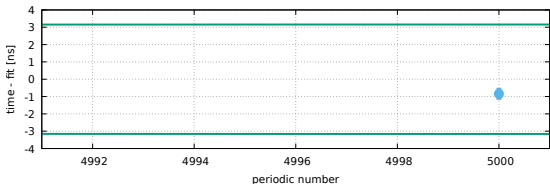
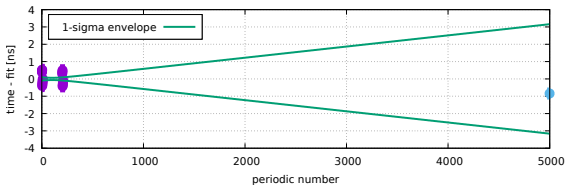
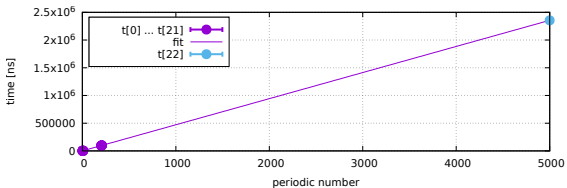
# Iterative Fit



- ▶ detect outlier caused by the closing gate on the input (no real zero-crossing)

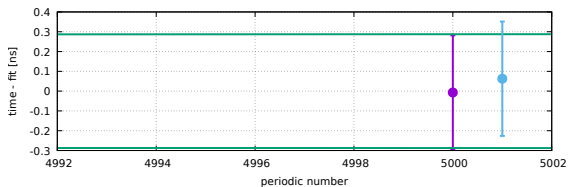
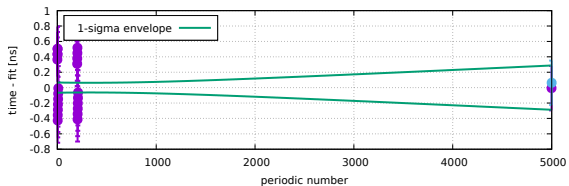
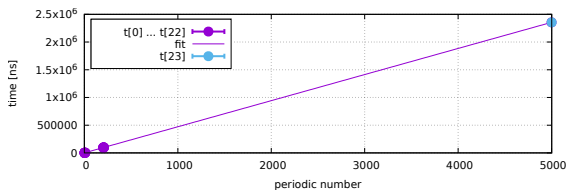


# Iterative Fit

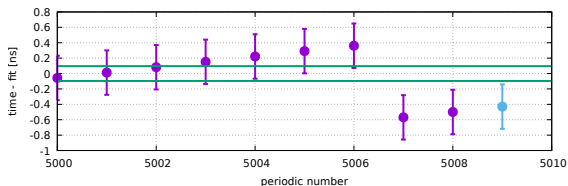
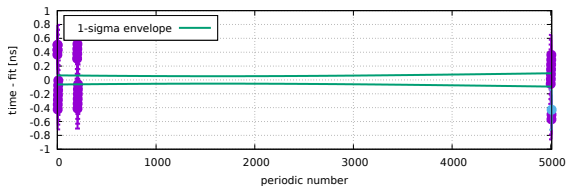
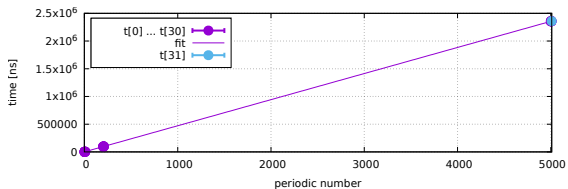


- ▶ fit to the previous data is good enough to bridge the gap to the next gate
- ▶ this allows to calculate the period number reliably

# Iterative Fit



# Iterative Fit



# Sub-ns Phase Fit on Embedded CPU in the B2B-PM Units

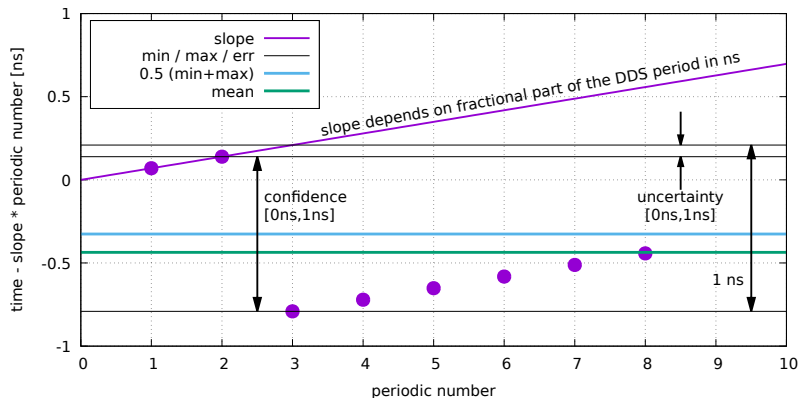
## Is 1 ns resolution enough?

- ▶ B2B transfer should hit a the bucket with 1 degree precision
- ▶ for  $\nu = 2 \text{ MHz}$  that is  $\approx 1.4 \text{ ns}$
- ▶ resolution of the timing receiver of 1 ns is (just) enough
- ▶ improve resolution using multiple zero-crossing measurements

## Phase Fit

- ▶ similar to frequency-phase fit seen before
- ▶ frequency is known, phase is the only free parameter
- ▶ should run on the LM32 CPU under real-time constraints

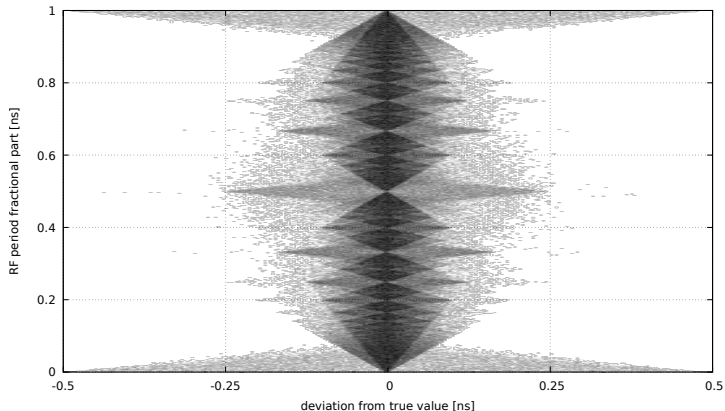
# Sub-ns Phase Fit Algorithm



Calculate phase position from min/max values

- ▶ more precise than mean value in case of finite data
- ▶ is simpler to compute: additions and shift operations
- ▶ result is reported in units of 125 ps (3 bits)

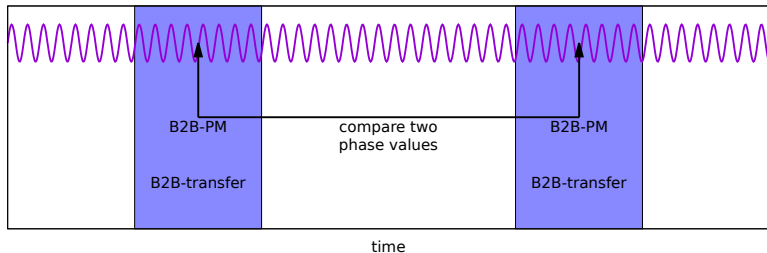
# Performance of the Algorithm



Accuracy depends on fractional part of RF-period (in ns)

- ▶ Worst case (no improvement) if fractional part is zero
- ▶ Maximum performance can be expected for small fractional parts, around 0.1 ns in this case

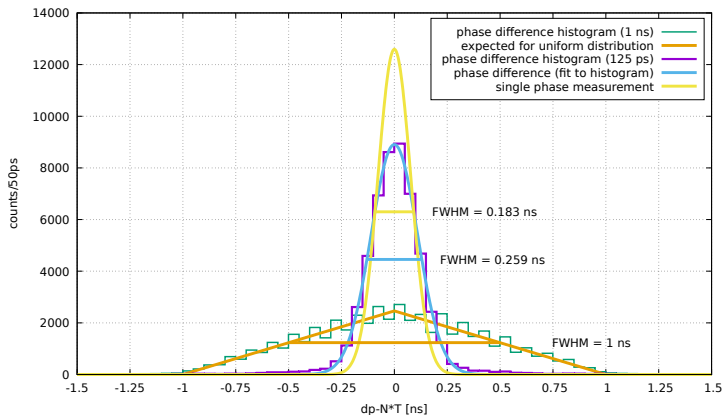
# First Test in Integration System



## B2B in the Integration System

- ▶ constant RF at flat-top frequency (from soft-clk-gen)
- ▶ regular B2B-transfers with phase fit
- ▶ evaluate differences of consecutive phase fit results
- ▶ width of the distribution depends on the accuracy of the phase fit result

# First Test Results (period=880.525ns freq: 1.13569 MHz)



For one fixed value of  $\nu$  (no ramps)

- ▶ difference between two consecutive phase values
- ▶ FWHM is improved by factor of 3.8