

# Pure LabVIEW Implementation of EPICS Communication Protocol



**Alexander Zhukov**

**Spallation Neutron Source,  
ORNL**

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# What is EPICS

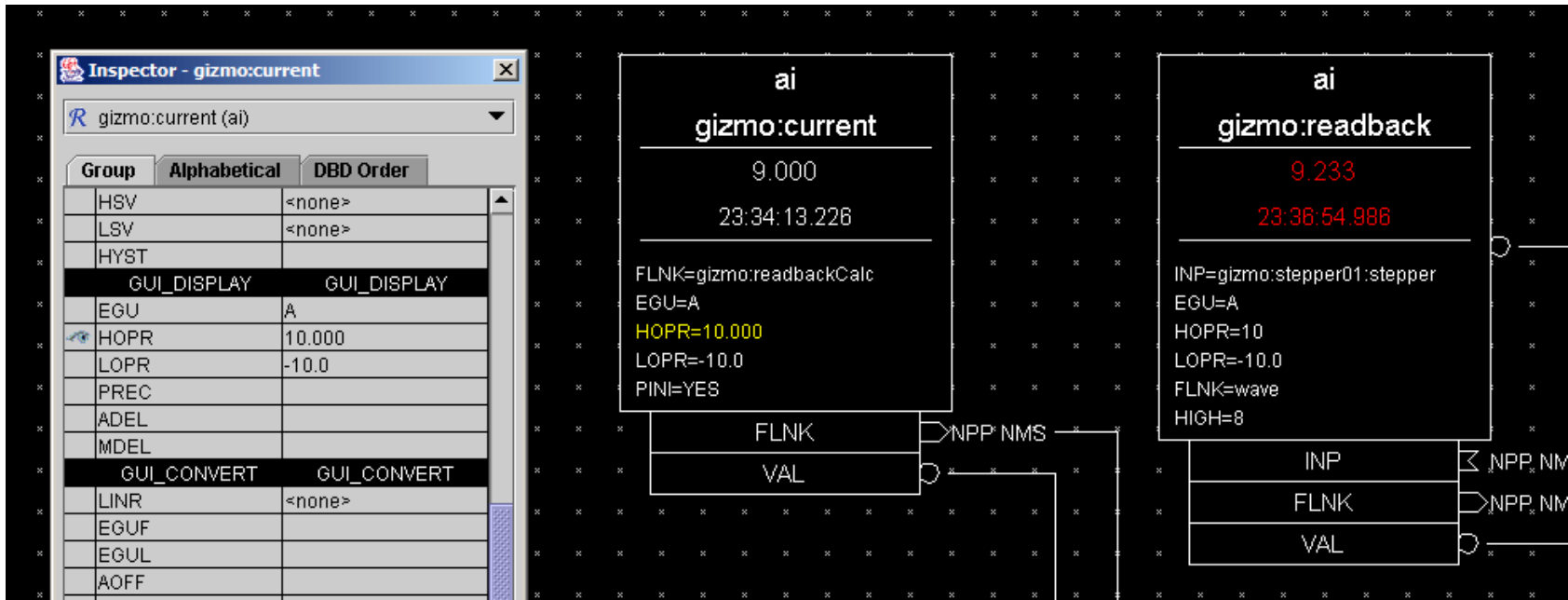
- **Experimental Physics and Industrial Control System (EPICS)** is a set of Open Source software tools, libraries and applications developed collaboratively and used worldwide to create distributed soft real-time control systems for scientific instruments such as a particle accelerators, telescopes and other large scientific experiments.
- **Major collaborators**
  - ANL
  - LANL
  - ORNL (SNS)
  - SLAC (SSRL, LCLS)
  - JLAB (CEBAF)
  - DESY
  - BESSY
  - PSI (SLS)
  - KEK
- **Runs on variety of hardware/OS (Linux, VxWorks, Windows, Mac, RTEMS...)**

# How EPICS works

- **A network based fully distributed client/server model**
- **Client and server use Channel Access (CA) protocol to communicate**
- **Everything spins around process variables (PV) – an entity similar to LabVIEW network shared variable**
  - A server (Input Output Controller – IOC) publishes data by updating PVs
  - PV corresponds to some value (measurement, setting, status etc)
  - Every PV has unique name
  - Client has ways to read PVs and update them over network
  - Client can subscribe to particular PV and monitor its value or state without polling it
- **Standard EPICS server also has records processing mechanism**
  - Control logic is programmed in records definition file
  - Allows perform routine tasks without explicitly programming in C
  - In addition to value every record has also status (OK, ALARMED, etc) and timestamp.

# Development process in EPICS

- Create a driver talking to hardware (device support) - C code
- Put high level code in EPICS records programming
- Different tools exist to simplify record programming including graphical ones where developer connects blocks with lines (looks familiar!)



# How to interface LabVIEW and EPICS

- We want to use LabVIEW for both low level and high level tasks, but still have connectivity with EPICS clients
- Several options exist
  - Windows shared memory (SNS)
  - National Instruments cRIO implementation of shared memory: full IOC runs on VxWorks (LANL)
  - National Instruments CA server shared variable engine extension
  - Simple Channel Access (SCA) OS specific (LBNL)
  - CaLab Windows DLL (BESSY)
  - LabVIEW Native Channel Access for EPICS LANCE (Observatory Sciences)
  - **Pure LabVIEW CA (SNS)**

**Pure LabVIEW solution uses standard Network Connectivity VIs that are available on all platforms where LabVIEW is supported. The same code written in LabVIEW communicates with EPICS clients. No C code involved at all!**

# CA protocol

- **Client wants to find out a value of a particular PV**
- **Client sends out UDP broadcast with PV name**
- **The server that has such PV replies**
- **Client checks if it already has TCP connection with this server**
- **If there is no such connection the client creates it**
- **If connection exists the client reuses existing connection**
- **After connection is established client exchanges messages with server over that connection.**

# LabVIEW implementation

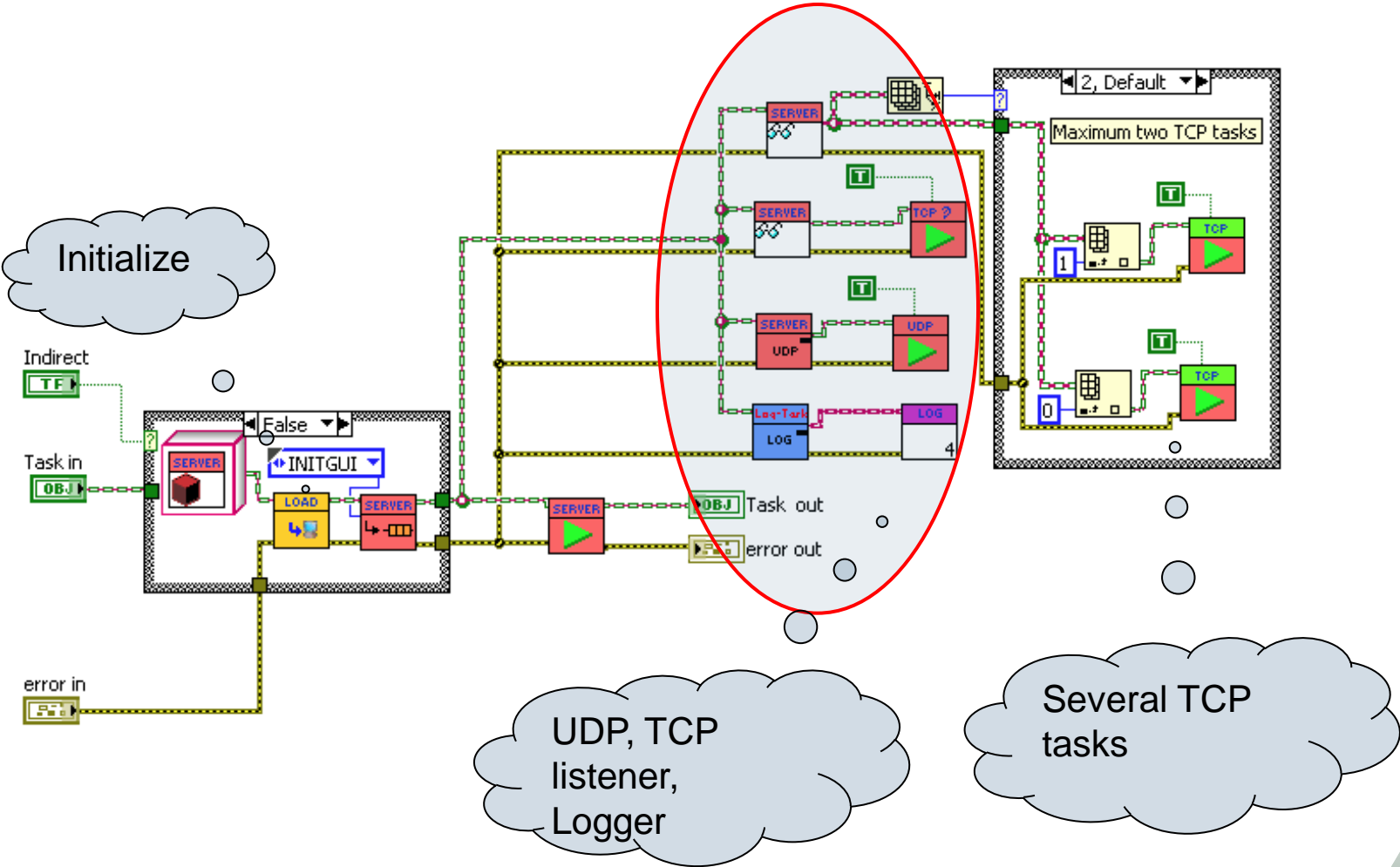
- **Uses UDP/TCP VIs**
- **Object Oriented design**
  - References to objects implemented using queues (compatible with 8.5 version)
  - Every PV type corresponds to a LabVIEW class (with common functionality pushed to base class)
  - Main Server class can be extended adding functionality without digging into internals
  - Logging exists as a separate service allowing different storage engines (text files, HTTP posts)
- **No dynamic thread allocation, instead everything is served by specified number of Worker Threads that check out established connections from connection pool and perform message processing if needed**
- **Naive implementation of standard Map (key-value pair )container in LabVIEW**
  - **All operations take  $O(N)$  in worst case**
  - **Heavy use of variant data type with casting**

# Code internals: Task class

- **Task class implements basic functionality of a task**
  - Reading config file and initializing settings
  - Has a stub for Run method
  - Handles closing the task correctly
  - Shows/hides front panel (for debug purposes)
  - Task can receive events from other tasks (using Queue VIs)
- **There are several task types all inheriting from Task (all are state machines)**
  - UDP task (listens to UDP requests from clients and if PV exists replies)
  - TCP listener task (listens to TCP connections and if established puts the associated object into a pool)
  - TCP task, many instances can be active (takes connection from the pool, checks if it needs processing and returns it back to the pool)
  - Logger Task (logs different events to a file or web server)

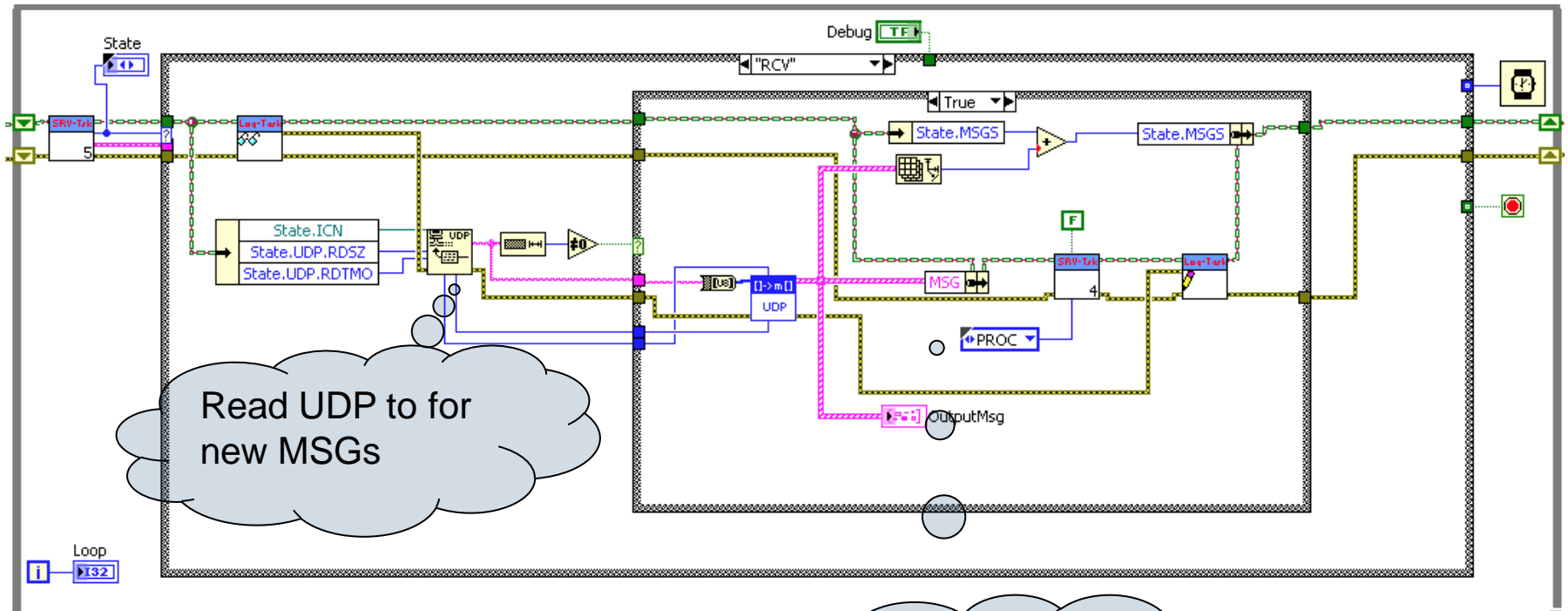


# Code internals: Launching all tasks



# Code internals: UDP Task

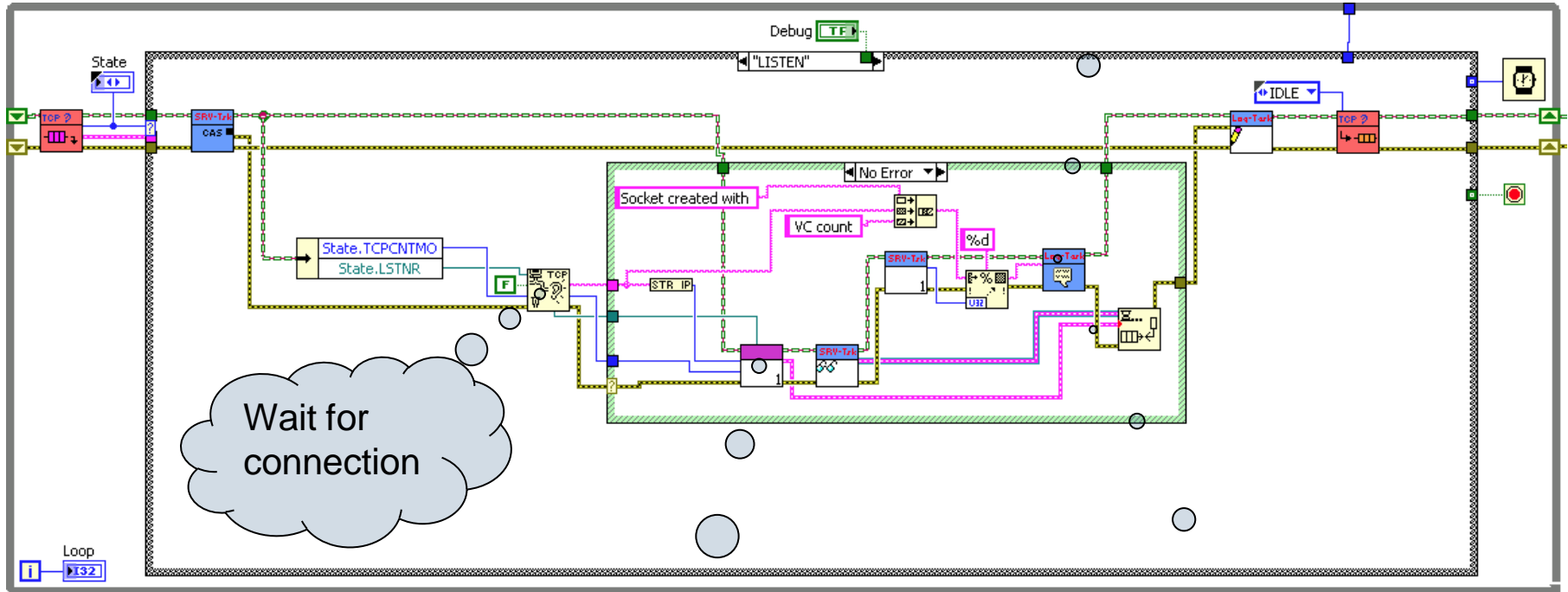
UDP Task listens to UDP port



# Code internals: TCP Listener Task

TCP listener task waits for TCP connection

Log event of connection creation



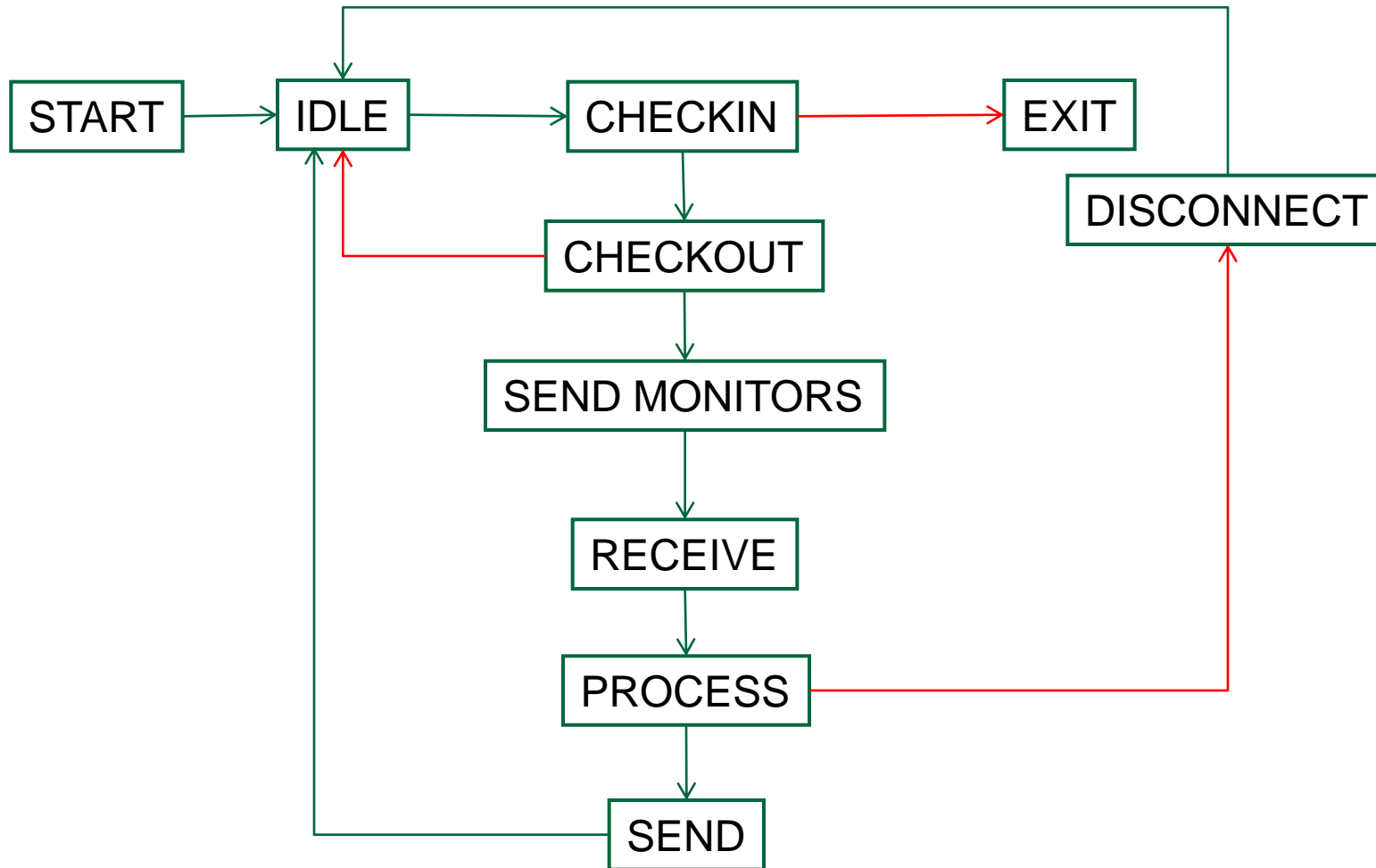
Wait for connection

If connection was established, create a new connection...

... and put it in the pool (queue)

# Code internals: TCP Task State Diagram

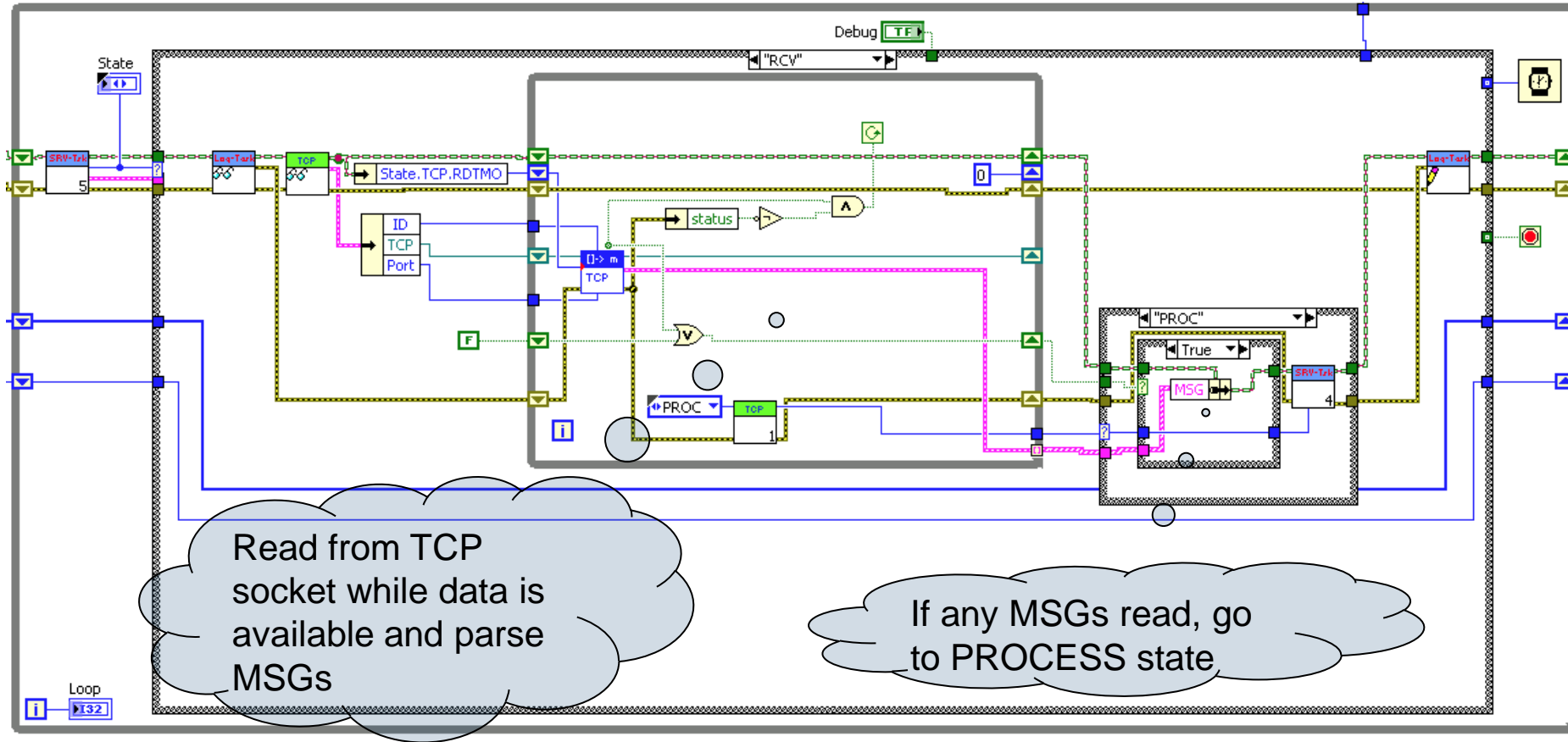
TCP Task processes connections. Several Tasks work with the same connection pool.



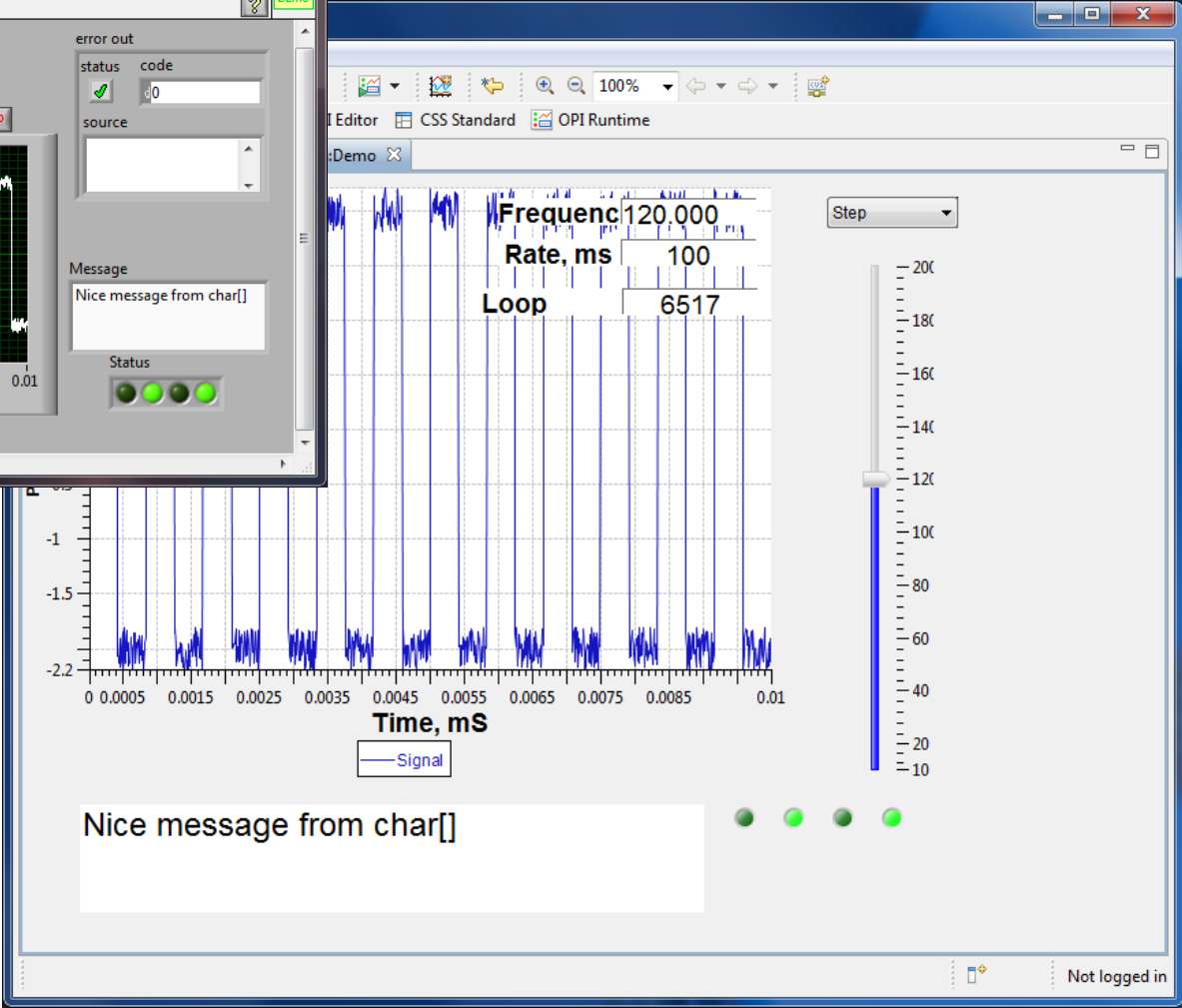
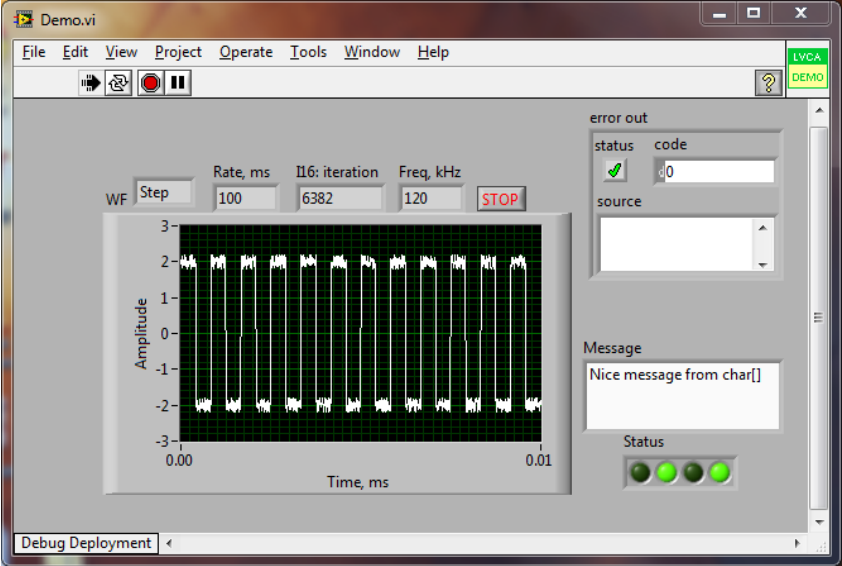
# Code internals: TCP Task

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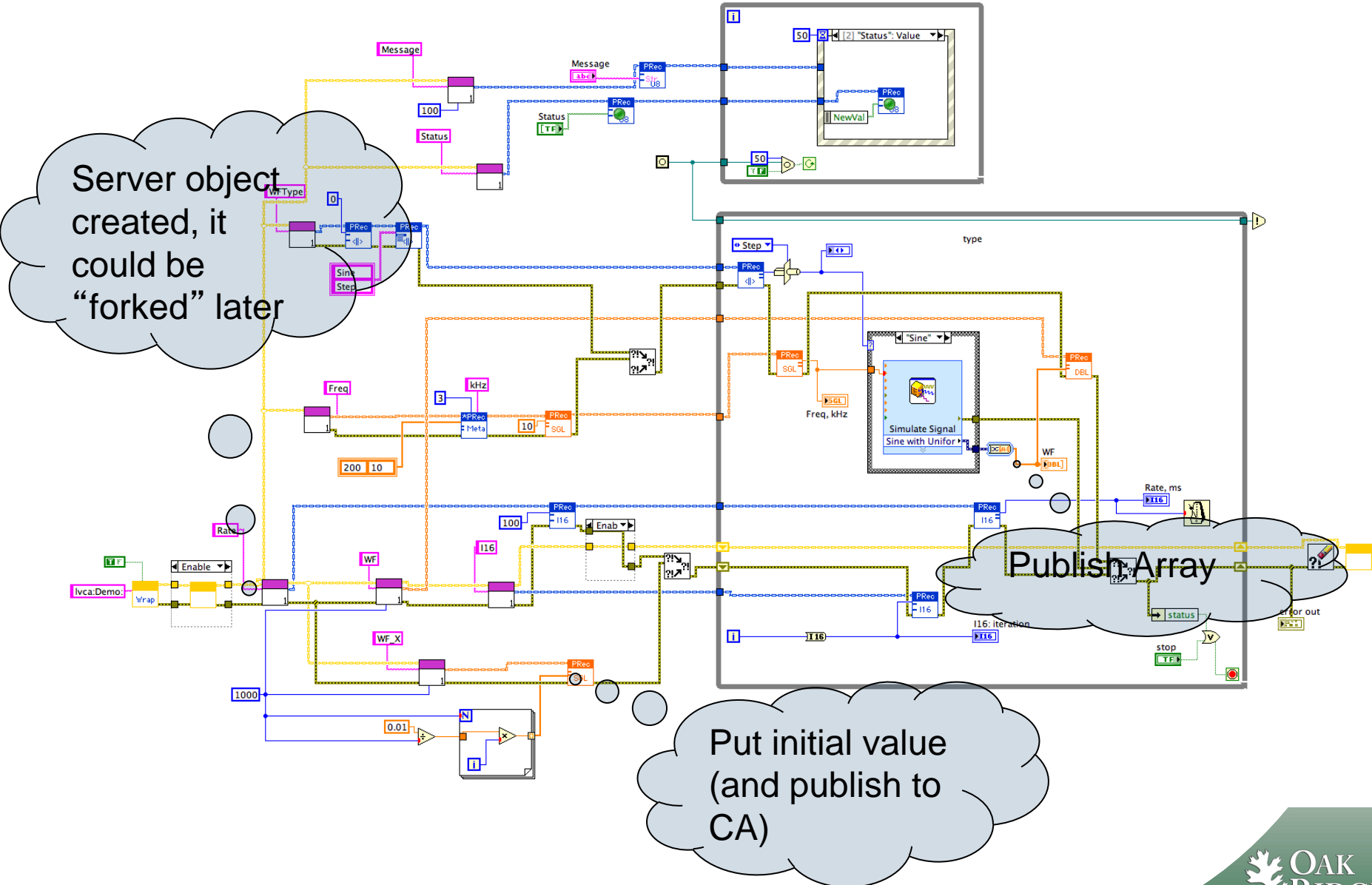
## TCP Task processes connections



# Demo server and GUI client



# Demo program structure



# Code internals: problems and challenges

- **Multi-threaded environment**

- Debugging is hard
- Profiling is hard and sometime inconsistent
- Queue operations are somewhat different (in terms of performance) on Windows and RT

- **LabVIEW limitations**

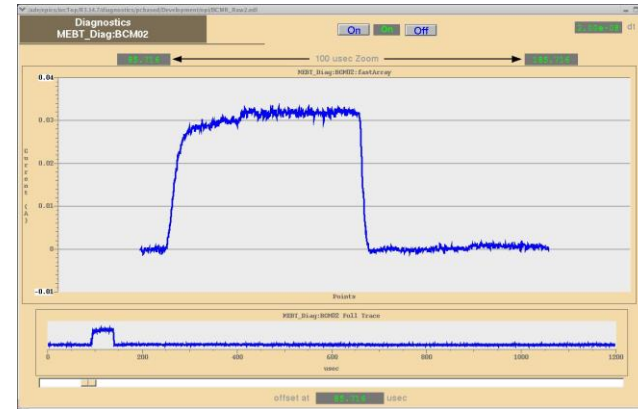
- OOP doesn't have multiple inheritance (Java style interfaces)
- No way to have custom C++ style template
- No standard containers (Vectors, Maps)



# Beam Diagnostics LabVIEW based instruments

- **Beam Instruments running on Windows at SNS**

- Beam Position Monitors
- Beam Current Monitors
- Wire scanners
- Laser profile monitors
- Video monitors
- Faraday Cups
- Emittance scanners



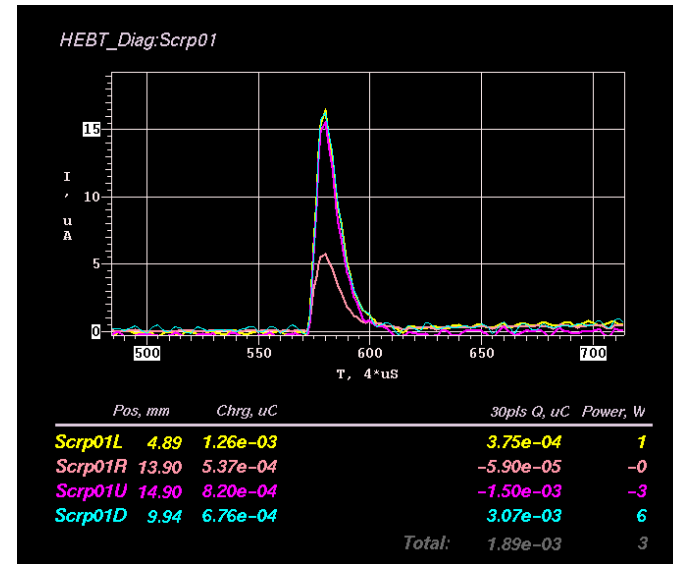
- **Instruments running on cRIO platform**

- Beam loss monitors
- Beam current monitor
- Collimator protection

- **Typical data acquisition rate**

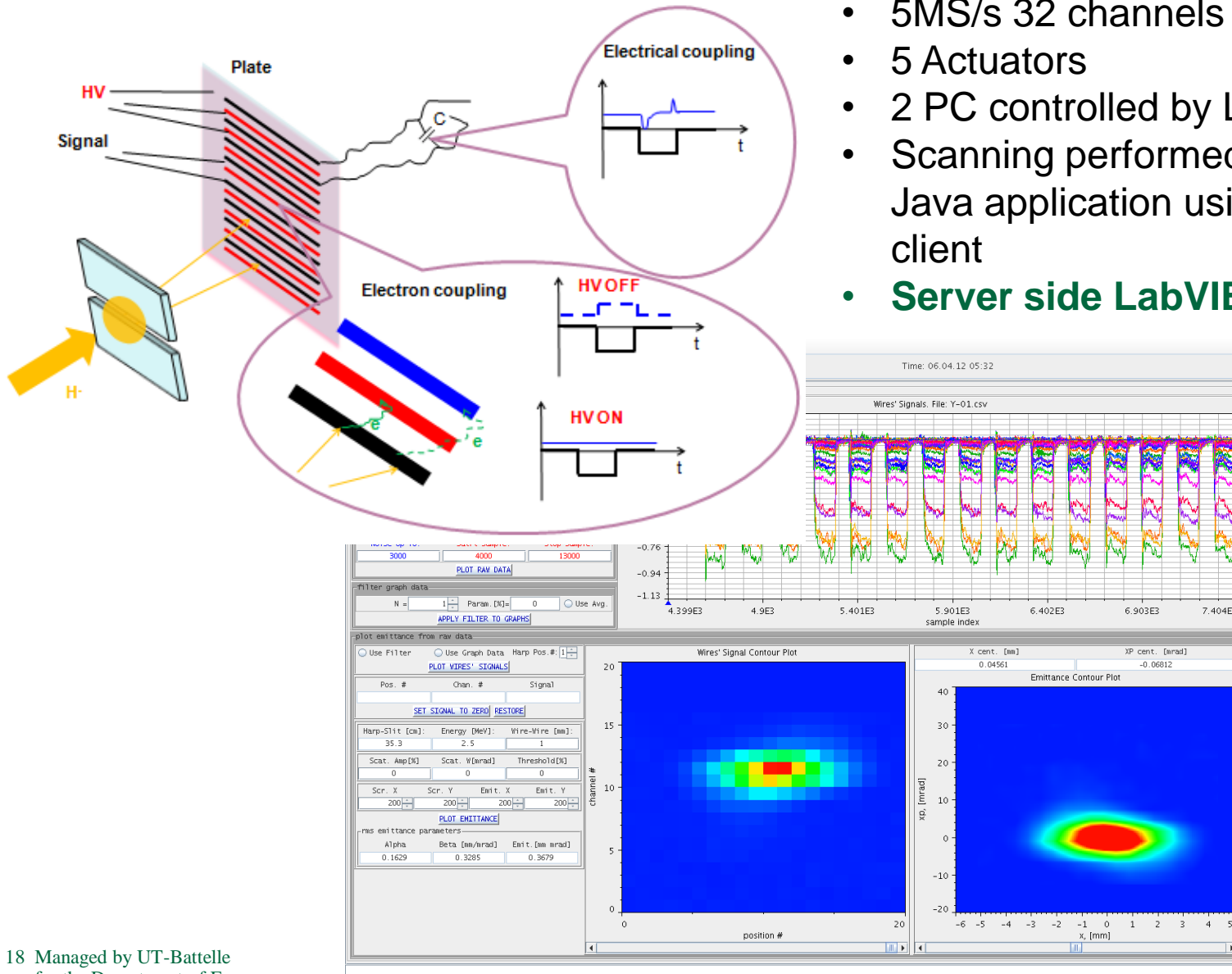
- 1Hz for Windows based devices
- 60Hz for cRIO

- **Publication rate almost always 1 Hz**



# Real life example of data acquisition

- 200 MS/s 1 channel or
- 5MS/s 32 channels
- 5 Actuators
- 2 PC controlled by LV
- Scanning performed by external Java application using EPICS client
- **Server side LabVIEW only!!!**



# Several instruments run this server implementation in production

- **PC based systems ~ 20 PCs total**
  - Laser profile scanners
  - Emittance scanners
  - Different attenuators
- **cRIO based systems 4 cRIO controllers total**
  - Collimator machine protection (with actual machine protection implemented in FPGA)

# Performance considerations

- **SNS typical numbers for “big” EPICS server**

- ~ 2k PVs
- ~ 16 channels x 1k points per second
- ~ 30 clients
- Under 10 Mbit/s

- **Performance**

- The biggest problem is setting up a test environment and test case
- Number of PVs, clients connected, PV update rate, PV (array) size, CPU power form at least 5-dimensional parameter configuration space
  
- one 1000 point WF at 300Hz/5 clients results in ~ 20% of CPU usage of iMAC with I7
- Two 20k point updated at 1 Hz uses ~5% of CPU on an average 4 yrs old industrial PC

# Summary

- Many LV EPICS interfaces exist
- There is no ideal one
- The need in full featured IOC is the key parameter for selection process
- Windows shared memory is still default way at SNS
- SNS pure LV version is cross-platform and seems to satisfy all needs, but is not finalized yet
  - **Beta testers needed!**
  - Client implementation is not ready yet
  - Performance tuning
  - Bad map implementation can become a bottleneck for servers hosting many (~5000 PVs) in busy networks
- The same programming technique can be used to implement any custom communication protocol
- LabVIEW can be used as general purpose programming tool and it is fast!

# Questions

